



GENERAL NAVIGATION HEADING AND POSITIONING COMPASS







Experience superior navigation from the accurate heading and positioning performance available with the Vector™ V200 GNSS compass. The multi-GNSS Vector V200 supports GPS, GLONASS, BeiDou, Galileo, and QZSS and offers an amazing world-wide 30 cm (RMS) accuracy via Hemisphere's Atlas GNSS global correction service.

The Vector V200 offers an incredible combination of simple installation, small form factor, and amazing performance. The compass - measuring only 35 cm in length - mounts easily to a flat surface or pole. The stability and maintenance-free design of the Vector V200 provides simple integration into autopilots, chart plotters, and AIS systems.

Key Features

- L1 GPS, GLONASS, Galileo, BeiDou, QZSS
- 50 cm RMS world-wide positioning accuracy with Atlas corrections
- 0.75 degree heading accuracy in an amazingly small form factor
- Excellent in-band and out-of-band interference rejection
- Integrated gyro and tilt sensors help deliver fast start-up times and provide heading updates during temporary loss of satellites
- Provides heading, positioning, heave, roll, and pitch

GNSS Sensor Specifications

Receiver Type: Vector GNSS L1 Receiver

Signals Received: GPS, GLONASS, BeiDou, Galileo, QZSS 7,

and Atlas

Channels: 424
GPS Sensitivity: -142 dBm

SBAS Tracking: 2-channel, parallel tracking
Update Rate: 10 Hz standard, 20 Hz optional

Timing (1 PPS)

Accuracy: 20 ns ⁶

Rate of Turn: 100°/s maximum

Compass Safe

Distance: 50 cm ⁴

Cold Start: 60 s (no almanac or RTC)
Warm Start: 30 s typical (almanac and RTC)

Hot Start: 10 s typical (almanac, RTC and position)

Heading Fix: 10 s typical (valid position)

Maximum Speed: 1,850 kph (999 kts)
Maximum Altitude: 18,288 m (60,000 ft)
Differential Options: SBAS, Atlas (L-band)

Accuracy

Default (RMS) Optional (RMS) Positioning: Autonomous, 1.2 m 1.2 m no SA: 1 SBAS: 2 $0.3 \, \text{m}$ $0.3 \, \text{m}$ Atlas: 6 $0.5 \, \mathrm{m}$ 1.5° Heading (RMS): 0.75° 1.5° Pitch/Roll (RMS): Heave (RMS): 30 cm (DGPS) ³ 30 cm (Atlas) 3.8

L-Band Receiver Specifications

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm Channel Spacing: 5 kHz

Satellite Selection: Manual or Automatic Reacquisition Time: 15 sec (typical)

Communications

Ports:

5-pin: NMEA2000

12-pin: RS-232 (2 Tx, 2 Rx), RS-422 (1 Tx), 1 PPS or

RS-422 (2 Tx, 1 Rx), 1 PPS

Baud Rates: 4800 - 115200

Correction I/O

Protocol: RTCM SC-104

Data I/O Protocol:

5-pin: NMEA 2000

12-pin: NMEA 0183, Crescent binary ⁵ Timing Output: 1 PPS (CMOS, rising edge sync ⁶)

1 Hemisphere

Power

Input Voltage: 6 to 36 VDC

Power Consumption: (multi-GNSS, typical continuous

draw @ 12V)

SBAS: 3.2 W **Atlas:** 3.6 W

Power Isolation: Isolated to enclosure

Reverse Polarity

Protection: Yes

Environmental

Operating

Temperature: -40°C to $+70^{\circ}\text{C}$ (-40°F to $+158^{\circ}\text{F}$) Storage Temperature: -40°C to $+85^{\circ}\text{C}$ (-40°F to $+185^{\circ}\text{F}$)

Humidity: 95% non-condensing

Enclosure: ISO 60529:2013 for IPx6/IPx7/IPx9
Vibration: IEC 60945:2002 Section 8.7 Vibration

EMC: IEC60945:2002

EN 301 489-1 V2.1.1 EN 301 489-5 V2.1.1 EN 301 489-19 V2.1.0 EN 303 413 V1.1.1

Mechanical

Dimensions:

 No Mount:
 $34.8 L \times 15.8 W \times 6.5 H (cm)$

 LP Flat Mount:
 $34.8 L \times 15.8 W \times 7.6 H (cm)$

 HP Flat Mount:
 $34.8 L \times 15.8 W \times 10.7 H (cm)$

 Pole Mount:
 $34.8 L \times 15.8 W \times 16.8 H (cm)$

Weight:

Not including Mount: 0.75 kg (1.7 lb) **Including Mount:** 0.94 kg (2.1 lb)

Power/Data

Connector: 5-pin or 12-pin

Aiding Devices

Gyro: Provides smooth heading, fast

heading reacquisition and reliable 1° per minute heading for periods up to 3 minutes when loss of GPS

has occurred

Till Sensors: Provide pitch and roll data and

assist in fast start-up and

reacquisition of heading solution

Depends on multipath environment, number of satellites in view, satellite geometry, no SA, and ionospheric activity

 Depends on multipath environment, number of satellites in view, WAAS coverage and satellite geometry

3. Based on a 40 second time constant

4. This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation

Hemisphere GNSS proprietary

6. V200s only

7. With future firmware upgrade and activation

8. Requires optional Atlas subscription

Hemisphere GNSS

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